· Formally tested electronics and firmware. Documented the design and created manuals with instructions for assembly and testing. Simplified the

Independently developed a control module for anchoring systems on small to medium-sized vessels. My design added many features including motor

PCB ordering process by automating manufacturing and assembly and wrote detailed documentation about the procedures. **Extracurricular Activities**

University of Auckland

Experience_

EMBEDDED SYSTEMS INTERN

Vetus - Maxwell

- Mentor
- Tutor students in both part I and part II in approaching problems involving circuit analysis, embedded design, and programming.

lockout at low voltage, fault detection/debugging, and a CAN section for communication to other devices while keeping costs low.

• Designed and implemented a testbench to drastically speed up assembly and testing of the control module.

• Act as a mentor and personal coach for students, helping motivate them, develop skills, set guidelines, and track their goals.

Rotary National Science and Technology Forum

PARTICIPANT

- One of 160 students selected nationally to attend the Forum.
- Learned about the most recent developments in science, mathematics and technology, gaining an insight into university life.

Projects

Portfolio

𝚱 HTTPS://VIKTORNESHIKJ.XYZ

- As an exercise to widen my skills in development, I taught myself React and JavaScript to build a portfolio for showcasing my projects.
- Taught myself wireframing using Figma and developed the outline based on Google Material Design guidelines, creating an aesthetic portfolio.

Inductive Drive RC Car

𝚱 HTTPS://GITHUB.COM/VNESHIKJ/INDUCTIVE-DRIVE-RC-CAR

- A wirelessly powered RC car developed in a pair. It features a custom-designed IPT pick-up regulator and DC-DC converter.
- Designed and tuned a secondary pick-up coil for harnessing power from the track through inductive coupling. Designed and implemented a buck converter, including the addition of a compensator, resulting in clean power output with minimal noise across all varying loads.
- Simulated and verified the designs using Plexim. Implemented the buck inductor based on magnetics design principles and also implemented overvoltage protection to protect the RC car.

Pathfinding Robot - Cypress PSoC 5

𝔗 HTTPS://GITHUB.COM/JAMESNZL/COMPSYS301-PATHFINDING-ROBOT

- A self-navigating robot developed in a team, utilising a PSoC 5 microcontroller.
- Designed analogue circuitry using photodiodes, tested using LTspice.
- Brainstormed and developed sensor constellation and layout.
- Designed and verified the PCB for the analogue circuitry using Altium.

AI Based Sign Language Interpreter

𝔗 HTTPS://GITHUB.COM/VNESHIKJ/ASL-INTERPRETER

- Developed an AI-based model to interpret American Sign Language in Python using PyTorch.
- Followed an MVC design pattern and developed the UI in Python using PyQt5.
- Collaborative project with two other individuals.

Inductive Energy Monitor

𝔗 HTTPS://GITHUB.COM/VNESHIKJ/ENERGY-MONITOR

- An embedded systems project monitoring the real time energy consumption of an inductive appliance.
- Designed and tested a custom PCB in Altium for signal sensing and conditioning. •
- Developed firmware in C for an ATmega328PB for digital signal processing and data transmission through UART.
- Led a team of four in an agile environment with weekly progress checkups.

Education_

University of Auckland

BACHELOR OF ENGINEERING (HONOURS) IN COMPUTER SYSTEMS, GPA: 7.5

Skills

Programming Languages: C, Python, Java, VHDL, MATLAB, R, LaTeX, Markdown, Javascript, CSS, HTML.

Technologies: Altium Designer, Quartus Prime, LTspice, PSoC Creator, Proteus, Git, GitHub, Figma, React.

Auckland, New Zealand

2023 - Present

Auckland, New Zealand

2023 - Present

2024

2023



Auckland, New Zealand

Jan 2021 - Present

Oct 2023 - Present

Auckland, New Zealand



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